

DYNAMIC ENGINEERING

150 DuBois, Suite 3
Santa Cruz, CA 95060
(831) 457-8891 **Fax** (831) 457-4793
<http://www.dyneng.com>
sales@dyneng.com
Est. 1988

Pc104plp

Driver Documentation

Win32 Driver Model

Revision A
Corresponding Hardware: Revision A
10-2005-0401
Corresponding Firmware: Revision A

Pc104plp
WDM Device Driver for the Pc104plp
PC104p based IP Carrier

Dynamic Engineering
150 DuBois, Suite 3
Santa Cruz, CA 95060
(831) 457-8891
FAX: (831) 457-4793

This document contains information of proprietary interest to Dynamic Engineering. It has been supplied in confidence and the recipient, by accepting this material, agrees that the subject matter will not be copied or reproduced, in whole or in part, nor its contents revealed in any manner or to any person except to meet the purpose for which it was delivered.

Dynamic Engineering has made every effort to ensure that this manual is accurate and complete. Still, the company reserves the right to make improvements or changes in the product described in this document at any time and without notice. Furthermore, Dynamic Engineering assumes no liability arising out of the application or use of the device described herein.

The electronic equipment described herein generates, uses, and can radiate radio frequency energy. Operation of this equipment in a residential area is likely to cause radio interference, in which case the user, at his own expense, will be required to take whatever measures may be required to correct the interference.

Dynamic Engineering's products are not authorized for use as critical components in life support devices or systems without the express written approval of the president of Dynamic Engineering.

This product has been designed to operate with IP Module carriers and compatible user-provided equipment. Connection of incompatible hardware is likely to cause serious damage.

©2007 by Dynamic Engineering.

Trademarks and registered trademarks are owned by their respective manufactures.
Manual Revision A. Revised April 16, 2007.



Table of Contents

Introduction	4
Note	4
Driver Installation	4
Windows 2000 Installation	5
Windows XP Installation	5
Driver Startup	6
IO Controls	9
IOCTL_PC104PIP_GET_INFO	9
IOCTL_PC104PIP_GET_SW_ID	9
IOCTL_PC104PIP_SET_BASE_CONFIG	10
IOCTL_PC104PIP_GET_BASE_CONFIG	10
IOCTL_PC104PIP_GET_INT_STATUS	10
IOCTL_PC104PIP_REGISTER_EVENT	10
IOCTL_PC104PIP_FORCE_INTERRUPT	11
IOCTL_PC104PIP_READ_ID_PROM	11
IOCTL_PC104PIP_RESET_ALL_IPS	11
IOCTL_PC104PIP_IDENTIFY	11
WARRANTY AND REPAIR	12
Service Policy	12
Out of Warranty Repairs	12
For Service Contact:	12

Introduction

The Pc104plp driver is a Win32 driver model (WDM) device driver for the Pc104plp Industry Pack (IP) carrier from Dynamic Engineering. Each Pc104plp board holds one IP module. When the Pc104plp is recognized by the PCI bus configuration utility it will load this driver and enumerate the Pc104plp's IP bus by reading the ID prom of the installed IP. If the IP device has been previously installed, its device driver will be loaded and a Device Object will be created for the installed IP. A separate handle to the Pc104plp and to the IP device can be obtained using CreateFile() calls (see below). IO Control calls (IOCTLs) are used to configure the Pc104plp and read status, although this is not necessary to operate the IP module. The Pc104plp is responsible for reading its user switch setting, operating the onboard LEDs, and a few other operations.

The Pc104plp's main function is to act as a PC104p<->IP Bus bridge device providing resources for the installed IP module, which independently operates through its own file handle. See the appropriate IP driver documentation for information on the capabilities of a particular IP module.

Note

This documentation will provide information about all calls made to the driver, and how the driver interacts with the device for each of these calls. For more detailed information on the hardware implementation, refer to the Pc104plp device user manual.

Driver Installation

There are several files provided in each driver package. These files include Pc104plp.sys, IpCarrier.inf, DDPc104plp.h, Pc104plpGUID.h, Pc104plpDef.h, Pc104plpTest.exe, and Pc104plpTest source files.

The DDPc104plp.h file is a C header file that defines the Application Program Interface (API) to the driver. The Pc104plpGUID.h file is a C header file that defines the device interface identifier for the Pc104plp. The Pc104plpDef.h file contains the relevant bit defines for the Pc104plp registers. These files are required at compile time by any application that wishes to interface with the Pc104plp driver, but are not needed for driver installation.

The Pc104plpTest.exe file is a sample Win32 console application that makes calls into the Pc104plp driver to test the driver calls without actually writing any application code. It is not required during the driver installation. Open a command prompt console window and type **Pc104plpTest -d0 -?** to display a list of commands (the Pc104plpTest.exe file must be in the directory that the window is referencing). The commands are all of the form **Pc104plpTest -dn -im** where **n** and **m** are the device number and driver ioctl number respectively



Windows 2000 Installation

Copy IpCarrier.inf and Pc104plp.sys to a floppy disk, or CD if preferred.

With the Pc104plp installed, power-on the PCI host computer and wait for the **Found New Hardware Wizard** dialogue window to appear.

- Select **Next**.
- Select **Search for a suitable driver for my device**.
- Select **Next**.
- Insert the disk prepared above in the desired drive.
- Select the appropriate drive e.g. **Floppy disk drives**.
- Select **Next**.
- The wizard should find the ipcarrier.inf file.
- Select **Next**.
- Select **Finish** to close the **Found New Hardware Wizard**.

Windows XP Installation

Copy IpCarrier.inf and Pc104plp.sys to a floppy disk, or CD if preferred.

With the Pc104plp installed, power-on the PCI host computer and wait for the **Found New Hardware Wizard** dialogue window to appear.

- Insert the disk prepared above in the desired drive.
- Select **No when asked to connect to Windows Update**.
- Select **Next**.
- Select **Install the software automatically**.
- Select **Next**.
- Select **Finish** to close the **Found New Hardware Wizard**.

At this point, if there is an IP module installed on the Pc104plp, the wizard will reactivate. The process for installing the IP driver is similar, and details can be found in the appropriate IP driver manual.

Driver Startup

Once the driver has been installed it will start automatically when the system recognizes the hardware.

A handle can be opened to a specific board by using the CreateFile() function call and passing in the device name obtained from the system.

The interface to the device is identified using a globally unique identifier (GUID), which is defined in Pc104pIpGUID.h.

Below is example code for opening a handle for device devNum.

```
// The maximum length of the device name for a given instance of an interface
#define MAX_DEVICE_NAME 256

// Handle to the device object
HANDLE hPc104pIp = INVALID_HANDLE_VALUE;

// Return status from command
LONG status;

// Handle to device interface information structure
HDEVINFO hDeviceInfo;

// The actual symbolic link name to use in the createfile
CHAR deviceName[MAX_DEVICE_NAME];

// Size of buffer required to get the symbolic link name
DWORD requiredSize;

// Interface data structures for this device
SP_DEVICE_INTERFACE_DATA interfaceData;
PSP_DEVICE_INTERFACE_DETAIL_DATA pDeviceDetail;

hDeviceInfo = SetupDiGetClassDevs(
    (LPGUID)&GUID_DEVINTERFACE_PC104PIP,
    NULL,
    NULL,
    DIGCF_PRESENT | DIGCF_DEVICEINTERFACE);

if(hDeviceInfo == INVALID_HANDLE_VALUE)
{
    printf("***Error: couldn't get class info, (%d)\n", GetLastError());
    exit(-1);
}
interfaceData.cbSize = sizeof(interfaceData);

// Find the interface for device devNum
if(!SetupDiEnumDeviceInterfaces(hDeviceInfo,
    NULL,
    (LPGUID)&GUID_DEVINTERFACE_PC104PIP,
```



```

        devNum,
        &interfaceData)
{
    status = GetLastError();
    if(status == ERROR_NO_MORE_ITEMS)
    {
        printf("***Error: couldn't find device(no more items), (%d)\n", devNum);
        SetupDiDestroyDeviceInfoList(hDeviceInfo);
        exit(-1);
    }
    else
    {
        printf("***Error: couldn't enum device, (%d)\n", status);
        SetupDiDestroyDeviceInfoList(hDeviceInfo);
        exit(-1);
    }
}

// Get the details data to obtain the symbolic link name
if(!SetupDiGetDeviceInterfaceDetail(hDeviceInfo,
                                    &interfaceData,
                                    NULL,
                                    0,
                                    &requiredSize,
                                    NULL))
{
    if(GetLastError() != ERROR_INSUFFICIENT_BUFFER)
    {
        printf("***Error: couldn't get interface detail, (%d)\n",
               GetLastError());

        SetupDiDestroyDeviceInfoList(hDeviceInfo);
        exit(-1);
    }
}

// Allocate a buffer to get detail
pDeviceDetail = (PSP_DEVICE_INTERFACE_DETAIL_DATA)malloc(requiredSize);
if(pDeviceDetail == NULL)
{
    printf("***Error: couldn't allocate interface detail\n");
    SetupDiDestroyDeviceInfoList(hDeviceInfo);
    exit(-1);
}

pDeviceDetail->cbSize = sizeof(SP_DEVICE_INTERFACE_DETAIL_DATA);

// Get the detail info
if(!SetupDiGetDeviceInterfaceDetail(hDeviceInfo,
                                    &interfaceData,
                                    pDeviceDetail,
                                    requiredSize,
                                    NULL,
                                    NULL))
{

```

```
printf("**Error: couldn't get interface detail(2), (%d)\n",  
        GetLastError());  
  
SetupDiDestroyDeviceInfoList(hDeviceInfo);  
free(pDeviceDetail);  
exit(-1);  
}
```

```

// Save the name
lstrcpyn(deviceName,
         pDeviceDetail->DevicePath,
         MAX_DEVICE_NAME);

// Cleanup search
free(pDeviceDetail);
SetupDiDestroyDeviceInfoList(hDeviceInfo);

// Open driver
// Create the handle to the device
hPc104pIp = CreateFile(deviceName,
                     GENERIC_READ | GENERIC_WRITE,
                     FILE_SHARE_READ | FILE_SHARE_WRITE,
                     NULL,
                     OPEN_EXISTING,
                     NULL,
                     NULL);

if(hPc104pIp == INVALID_HANDLE_VALUE)
{
    printf("**Error: couldn't open %s, (%d)\n", deviceName,
          GetLastError());
    exit(-1);
}

```

IO Controls

The driver uses IO Control calls (IOCTLs) to configure the device. IOCTLs refer to a single Device Object in the driver, which controls a single board. IOCTLs are called using the Win32 function DeviceIoControl(), and passing in the handle to the device opened with CreateFile(). IOCTLs generally have input parameters, output parameters, or both. Often a custom structure is used.

IOCTL_PC104PIP_GET_INFO

Function: Returns the current driver version and instance number.

Input: None

Output: DRIVER_CARRIER_DEVICE_INFO structure

Notes: This call does not access the hardware, only driver parameters. See DDPc104plp.h for the definition of DRIVER_CARRIER_DEVICE_INFO.

IOCTL_PC104PIP_GET_SW_ID

Function: Reads the eight-position onboard dipswitch.

Input: None

Output: Switch value (unsigned long integer)



Notes: The switch can be used for any purpose that the user wishes. It can uniquely identify the boards installed in a chassis, or be used to distinguish configuration classes to the user's application software.

IOCTL_PC104PIP_SET_BASE_CONFIG

Function: Writes to the base configuration register on the Pc104plp.

Input: Register configuration value (unsigned long integer)

Output: None

Notes: This call is used to control the eight LEDs on the board, the interrupt enables and the bus error interrupt clear. The bus error and master interrupt enables default to TRUE when the driver initializes, however they can be disabled using this call. Be aware that if this is done it will disable the interrupts of the IP installed on the carrier. If the bus error interrupt clear is written as a one to clear the latched bus error status, it will be automatically cleared and does not need to be re-written as a zero.

IOCTL_PC104PIP_GET_BASE_CONFIG

Function: Returns the configuration of the base control register.

Input: None

Output: Register configuration value (unsigned long integer)

Notes: This call is used mainly for testing.

IOCTL_PC104PIP_GET_INT_STATUS

Function: Returns the IP interrupt status.

Input: None

Output: Interrupt status register value (unsigned long integer)

Notes: Returns the masked and unmasked interrupt status for the IP slot as well as the bus error interrupt and combined status. See Pc104plpDef.h for details on all the status bits.

IOCTL_PC104PIP_REGISTER_EVENT

Function: Registers an event to be signaled when an interrupt occurs.

Input: Handle to Event object

Output: None

Notes: The caller creates an event with CreateEvent() and supplies the handle returned from that call as the input to this IOCTL. The driver then obtains a system pointer to the event and signals the event when an interrupt is serviced. The user interrupt service routine waits on this event, allowing it to respond to the interrupt. Please note that the Pc104plp only handles the bus error interrupt and its own force interrupt, the IP interrupts are handled by the individual IP driver and will not cause the event to be signaled.



IOCTL_PC104PIP_FORCE_INTERRUPT

Function: Causes a system interrupt to occur.

Input: None

Output: None

Notes: Causes an interrupt to be asserted on the PCI bus as long as the master interrupt has not been disabled. This IOCTL is used for development, to test interrupt processing.

IOCTL_PC104PIP_READ_ID_PROM

Function: Returns the contents of the IP ID prom.

Input: None

Output: IP ID PROM contents (ID_DATA structure)

Notes: Returns the contents of the IP ID prom. The ID_DATA structure is returned. This structure contains two Boolean fields that indicate if the IP prom is valid and if it is capable of 32 MHz operation. It also contains a 12-element array of UCHAR that has the ID prom contents, provided the prom was found to be valid. See DDPc104plp.h for the structure definition.

IOCTL_PC104PIP_RESET_ALL_IPS

Function: Resets the IP slot.

Input: None

Output: None

Notes: Resets the IP slot by setting and then clearing the BASE_RESET_ALL_IPS bit in the base configuration register. This bit cannot be controlled by the IOCTL_PC104PIP_SET_BASE_CONFIG call.

IOCTL_PC104PIP_IDENTIFY

Function: Flashes all user LEDs three times.

Input: None

Output: None

Notes: This call can be used when more than one device is installed in a chassis and it is desired to identify the physical location of a particular device.

Warranty and Repair

Dynamic Engineering warrants this product to be free from defects under normal use and service and in its original, unmodified condition, for a period of one year from the time of purchase. If the product is found to be defective within the terms of this warranty, Dynamic Engineering's sole responsibility shall be to repair, or at Dynamic Engineering's sole option to replace, the defective product.

Dynamic Engineering's warranty of and liability for defective products is limited to that set forth herein. Dynamic Engineering disclaims and excludes all other product warranties and product liability, expressed or implied, including but not limited to any implied warranties of merchandisability or fitness for a particular purpose or use, liability for negligence in manufacture or shipment of product, liability for injury to persons or property, or for any incidental or consequential damages.

Dynamic Engineering's products are not authorized for use as critical components in life support devices or systems without the express written approval of the president of Dynamic Engineering.

Service Policy

Before returning a product for repair, verify as well as possible that the driver is at fault. The driver has gone through extensive testing and in most cases it will be a "cockpit error" rather than an error with the driver. When you are sure or at least willing to pay to have someone help then call the Customer Service Department and arrange to speak with an engineer. We will work with you to determine the cause of the issue. If the issue is one of a defective driver we will correct the problem and provide an updated module(s) to you [no cost]. If the issue is of the customer's making [anything that is not the driver] the engineering time will be invoiced to the customer. Pre-approval may be required in some cases depending on the customer's invoicing policy.

Out of Warranty Repairs

Out of warranty support will be billed. The current minimum repair charge is \$125. An open PO will be required.

For Service Contact:

Customer Service Department
Dynamic Engineering
150 DuBois, Suite 3
Santa Cruz, CA 95060
(831) 457-8891 Fax (831) 457-4793
support@dyneng.com

All information provided is Copyright Dynamic Engineering

